



### AutoBench™ Version 1.1

### Benchmark Name: Infinite Impulse Response (IIR) Filter

**Benchmark Description**

This Embedded Microprocessor Benchmark Consortium (EEMBC) benchmark algorithm simulates an embedded automotive/industrial application where the CPU performs an Infinite Impulse Response (IIR) filtering sample on 16-bit or 32-bit fixed-point values. It implements a Direct-Form II N-cascaded, second-order IIR filter. IIR filters can often be more efficient than FIR filters, in terms of attaining better magnitude response with a given filter order. This is because IIR filters incorporate feedback and are capable of realizing both poles and zeros of a system, whereas FIR filters are not capable of realizing the zeros. The difference equation for a Direct Form II N-Cascaded Direct second-order IIR filter is:

$$\begin{aligned} \{u(n) &= x(n) + a(1)*x(n-1) + a(2)*x(n-2), \\ \{y(n) &= b(0)*u(n) + b(1)*u(n-1) + b(2)*u(n-2); \end{aligned}$$

where:

- x(n) = input signal of the biquad at time n
- u(n) = state variable of the biquad at time n
- y(n) = output signal of the biquad at time n
- a(n), b(n) = coefficients of the biquad

High- and low-pass IIR filters process the input signal data. Binary comparators also digitize the outputs of the filters. This IIR filter benchmark explores a CPU's ability to perform multiply-accumulates and rounding. It employs typical DSP functions that would replace an analog signal chain comprised of op-amps and comparators.

**Optimization Rules**

Category	Allowed	Disallowed
ANSI C	X	
Intrinsics/Language Extensions	X	
Custom Libraries	X	
Assembly Language	X	
HW Accelerators	X	

**Algorithm Flowchart (page 2)**

**Algorithm  
Flowchart**

